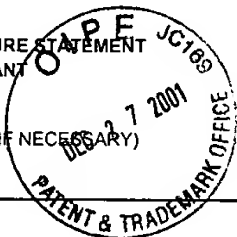


FORM PTO-1449	U.S. DEPARTMENT OF COMMERCE PATENT AND TRADEMARK OFFICE	ATTY. DOCKET NO. PRSROB.003A	APPLICATION NO. 09/847,598
INFORMATION DISCLOSURE STATEMENT BY APPLICANT		APPLICANT Koselka, et al.	
(USE SEVERAL SHEETS IF NECESSARY)		FILING DATE May 02, 2001	GROUP 2837



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EXAMINER INITIAL		DOCUMENT NUMBER	DATE	NAME	CLASS	SUBCLASS	FILING DATE (IF APPROPRIATE)
PLM	1.	1,130,064	03/02/15	Buchanan	15	228	
PLM	2.	4,510,642	04/16/85	Ingermann, et al.	15	231	
PLM	3.	4,550,467	11/05/85	Johnson, et al.	15	228	
PLM	4.	4,647,784	03/03/87	Stephens	250	561	
PLM	5.	4,709,265	11/24/87	Silverman, et al.	358	108	
PLM	6.	4,852,210	08/01/89	Krajicek	15	228	
PLM	7.	5,071,489	12/10/91	Silvenis, et al.	134	42	
PLM	8.	5,086,262	02/04/92	Hariki, et al.	318	568.1	
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PLM	10.	5,179,329	01/12/93	Nishikawa, et al.	318	587	
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PLM	15.	5,382,885	01/17/95	Salcudean, et al.	318	568.11	
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PLM	21.	5,825,149	10/20/98	Matsumoto, et al.	318	587	
PLM	22.	5,825,813	10/20/98	Na	375	219	
PLM	23.	5,825,981	10/20/98	Matsuda	395	83	
PLM	24.	5,867,800	02/02/99	Leif	701	23	
PLM	25.	5,968,281	10/19/99	Wright, et al.	134	6	
PLM	26.	5,991,951	11/30/99	Kubo, et al.	15	50.1	
PLM	27.	6,101,671	08/15/00	Wright, et al.	15	365	

EXAMINER

Patricia M. Hill

DATE CONSIDERED

10-1-02

\*EXAMINER: INITIAL IF CITATION CONSIDERED, WHETHER OR NOT CITATION IS IN CONFORMANCE WITH MPEP 609; DRAW LINE THROUGH CITATION IF NOT IN CONFORMANCE AND NOT CONSIDERED. INCLUDE COPY OF THIS FORM WITH NEXT COMMUNICATION TO APPLICANT.

FORM PTO-1449	U.S. DEPARTMENT OF COMMERCE PATENT AND TRADEMARK OFFICE	ATTY. DOCKET NO. PRSR08.003A	APPLICATION NO. 09/647,598
<b>INFORMATION DISCLOSURE STATEMENT BY APPLICANT</b>  (USE SEVERAL SHEETS IF NECESSARY)		APPLICANT Koselka, et al.	
		FILING DATE May 02, 2001	GROUP 2837



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EXAMINER INITIAL		DOCUMENT NUMBER	DATE	NAME	CLASS	SUBCLASS	FILING DATE (IF APPROPRIATE)
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PLM	29.	"Robot Spatial Perception by Stereoscopic Vision and 3D Evidence Grids" by Hans Moravec, Robotics Institute, Carnegie Mellon University, Pittsburgh, PA September 1996.
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PLM	44.	Rekleitis, et al., "Multi-Robot Exploration of an Unknown Environment, Efficiently Reducing the Odometry Error", 1997.
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EXAMINER	<i>Patricia Miller</i>	DATE CONSIDERED	10-1-02
*EXAMINER: INITIAL IF CITATION CONSIDERED, WHETHER OR NOT CITATION IS IN CONFORMANCE WITH MPEP 609; DRAW LINE THROUGH CITATION IF NOT IN CONFORMANCE AND NOT CONSIDERED, INCLUDE COPY OF THIS FORM WITH NEXT COMMUNICATION TO APPLICANT.			